CRACK DETECTION IN CONCRETE SURFACES USING IMAGE PROCESSING, FUZZY LOGIC, AND NEURAL NETWORKS

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INTRODUCTION: NEED

• Structural health monitoring (SHM):

- Skilled labor
- Time consuming
- Costly

• SHM in inaccessible or dangerous areas

- Sewers
- Nuclear reactors

INTRODUCTION: PREVIOUS WORK

- Initial work focus solely on image processing.
- Kaseko *et al*.: Neural network
- Chae *et al.*: Neuro-fuzzy system
- Fujita *et al.*: Probabilistic relaxation, local thresholding, and 3 measures of accuracy - sensitivity, specificity and precision
- Sinha *et al.*: Neuro-fuzzy model, *type* of crack
- Moon and Kim: Neural network with 5 hidden layers with image-wise accuracy as measure

OBJECTIVES

- Comparative study of different types of approaches to crack detection
- Studying various measures of model performance
- Investigate the effect of output thresholds on performance measures
- Novel model based purely on fuzzy logic, unlike previous neuro-fuzzy approaches
- Comparative study of effect of size of neural networks on performance measures
- Comparative study of edge detection, median filter, Gaussian filter, etc. on performance measures





IMAGE PROCESSING: EXAMPLE











Base Image Source:

http://static5.depositpho tos.com/1013817/399/i/9 50/depositphotos_39928 92-Elegant-split-crackin-concrete.jpg

APPROACHES TOWARD MODEL DEVELOPMENT

- Object approach
- o Image approach
- Threshold fine-tuning
- Performance measures:
 - Sensitivity
 - Specificity
 - Precision
 - Image-wise accuracy
 - Object-wise accuracy

FUZZY LOGIC MODEL (OBJECT APPROACH)

O Mamdani fuzzy inference system

• Membership functions:

- Input Variables
 - Area low, moderate, and high
 - Major-to-minor axes ratio low and high
- Output Variable:
 - Class Noise and crack
- 'Min' implication for 'AND' operator
- 'Max' aggregation with 'centroid' defuzzification

NEURAL NETWORK APPROACHES

• Image approach architectures:

- 100 50 50 50 1
- 100 10 10 10 10 1
- 100 5 5 5 5 5 1
- 100 5 5 5 5 5 5 1

Object approach architectures:

• $2 - \mu - 1$, where $20 \le \mu \le 1$

• Single neuron output between 0 and 1

 ${\rm o}$ Threshold value $0<\alpha<1$ must be chosen to differentiate between cracks and noise

IMAGE APPROACH: NETWORK PROPERTIES

- Feed forward back propagation
- Training function:
- Transfer function:
- Learning rate:
- Momentum:
- Maximum epochs:
- Training:
- Testing:
- Validation:

Scaled conjugate gradient Log-sigmoid function 0.01 0.910000 70% of samples. 15% of samples. 15% of samples.

IMAGE APPROACH: NETWORK PROPERTIES

o Input: 100 neurons

- Area of 50 objects per image (in descending order)
- Major-to-minor axes ratios corresponding to (descending) area of each object per image
- o 3 to 6 hidden layers
- Equal number of hidden neurons multiples of 5
- Output: 1 neuron
 - 1 Crack
 - 0 Noise

OBJECT APPROACH: 2-CLASS CLASSIFICATION



OBJECT APPROACH: IMBALANCE IN DATASET

12000 noise : 300 cracks reduced to 400 noise : 300 cracks
70% of noise above line, 7.5% of noise below.



OBJECT APPROACH: NETWORK PROPERTIES

- Feed forward back propagation
- Training function:
- Transfer function:
- Maximum epochs:
- Training:
- Testing:
- Validation:

Scaled conjugate gradient Log-Sigmoid activation 10000 70% of samples 15% of samples 15% of samples

OBJECT APPROACH: NETWORK PROPERTIES

o Input: 2 neurons

- Area of an object
- Major-to-minor axes ratio of that object
- Single hidden layer with 1 to 20 neurons
- Output: 1 neuron
 - 1 Crack
 - 0 Noise

OBJECT APPROACH: FINALIZING MODELS



RESULTS: MEASURES

• Image – wise accuracy = $\frac{\text{Images correctly classified}}{\text{Total number of images}}$

• Object – wise accuracy = $\frac{\text{Objects correctly classified}}{\text{Total number of objects}}$

• Sensitivity = $\frac{\text{Cracks correctly classified}}{\text{Total cracks}}$

• Specificity = $\frac{\text{Noise correctly classified}}{\text{Total noise}}$

• Precision = $\frac{\text{Cracks correctly classified}}{\text{Total objects classified as cracks}}$

ARCHITECTURE SELECTION: OBJECT APPROACH

NO. OF HIDDEN NODES	SENSITIVITY	Specificity	PRECISION	IMAGE-WISE ACCURACY	OBJECT-WISE ACCURACY
1	0.1923	0.9997	0.9259	0.8667	0.9835
2	0.2692	0.9991	0.8642	0.8952	0.9845
3	0.5692	0.9959	0.7400	0.8286	0.9874
4	0.5731	0.9960	0.7450	0.8286	0.9875
5	0.5615	0.9966	0.7725	0.8571	0.9879
6	0.5731	0.9966	0.7760	0.8476	0.9881
7	0.5615	0.9965	0.7684	0.8667	0.9878
8	0.5808	0.9965	0.7704	0.8571	0.9881
9	0.5654	0.9962	0.7538	0.8286	0.9876
10	0.5577	0.9974	0.8146	0.8952	0.9886
11	0.5731	0.9965	0.7680	0.8571	0.9880
12	0.5577	0.9970	0.7923	0.8762	0.9882
13	0.5808	0.9966	0.7784	0.8667	0.9883
14	0.5769	0.9964	0.7653	0.8667	0.9880
15	0.5731	0.9969	0.7884	0.8762	0.9884
16	0.5769	0.9965	0.7692	0.8571	0.9881
17	0.5615	0.9966	0.7725	0.8667	0.9879
18	0.5654	0.9969	0.7903	0.8571	0.9883
19	0.5731	0.9964	0.7641	0.8571	0.9879
20	0.5615	0.9969	0.7892	0.8762	0.9882

THRESHOLD FOR NN OBJECT APPROACH

THRESHOLD	SENSITIVITY	SPECIFICITY	PRECISION	IMAGE-WISE ACCURACY	OBJECT-WISE ACCURACY
0.65	0.5462	0.9975	0.8161	0.8857	0.9884
0.66	0.5462	0.9975	0.8161	0.8857	0.9884
0.67	0.5423	0.9975	0.8150	0.8857	0.9884
0.68	0.5385	0.9977	0.8284	0.8952	0.9885
0.69	0.5308	0.9980	0.8466	0.9048	0.9887
0.70	0.5269	0.9980	0.8457	0.9048	0.9886
0.71	0.5269	0.9981	0.8509	0.9143	0.9887
0.72	0.5231	0.9982	0.8553	0.9238	0.9887
0.73	0.5115	0.9983	0.8581	0.9238	0.9885
0.74	0.5077	0.9983	0.8571	0.9238	0.9884
0.75	0.5000	0.9983	0.8609	0.9238	0.9884
0.76	0.4962	0.9984	0.8658	0.9238	0.9884
0.77	0.4885	0.9984	0.8639	0.9238	0.9882
0.78	0.4885	0.9985	0.8699	0.9238	0.9883
0.79	0.4885	0.9987	0.8819	0.9333	0.9884
0.80	0.4808	0.9987	0.8865	0.9429	0.9884
0.81	0.4808	0.9988	0.8929	0.9524	0.9884
0.82	0.4692	0.9988	0.8905	0.9524	0.9882
0.83	0.4538	0.9990	0.9008	0.9619	0.9881
0.84	0.4462	0.9991	0.9063	0.9619	0.9880
0.85	0.4423	0.9991	0.9055	0.9524	0.9879

COMPARISON WITH PREVIOUS WORK

Comparison with Fujita et al. [8]:						
THRESHOLD	Sensitivity	Specificity	Precision	IMAGE-WISE ACCURACY	Object-wise Accuracy	
Sample threshold for the proposed model:						
0.25	0.792	0.989	0.592	0.733	0.985	
Best results reported by Fujita et al. [8]:						
-	0.722	0.993	0.655	Global Thresholding		
-	0.815	0.922	0.147	Local Thresholding		
-	0.805	0.992	0.631	Probabilistic Relaxation		

COMPARISON WITH PREVIOUS WORK

Comparison with Moon et al. [11]:					
Approach Type	Models	Threshold α	IMAGE-WISE ACCURACY		
Image	3 Hidden Layer NN	0.32	87.00		
Image	4 Hidden Layer NN	0.41	86.00		
Image	5 Hidden Layer NN	0.44	85.00		
Image	6 Hidden Layer NN	0.70	93.00		
Object	'2-13-1' NN	0.83	96.00		
Object	Fuzzy Logic Model	0.68	94.00		
Image	NN of Moon et al. [11]	-	90.25		

DISCUSSION: ACCURACY

o Inverse proportionality:

- Sensitivity and Specificity
- Sensitivity and Precision
- Sensitivity and Image-wise accuracy (below the optimum threshold)
- At threshold = 0 or 1, sensitivity = 1 or 0 and specificity = 0 or 1, respectively.

 Maxima of all measures attained at different thresholds

DISCUSSION: IMAGE PROCESSING

Image Processing

- Fragmentation of cracks: Reason for low sensitivity
- Sobel edge detection: Shadows, color changes as edge
- Consider R,G and B separately

Object Parameters

- Sensitivity of all models low
- Area and ratio alone not sufficient: Need additional parameters

CONCLUSION

- All 5 measures of performance important
- Object approach better than Image approach for all models
- Neural network models better than fuzzy logic model in all measures of performance, especially sensitivity
- For image approach, edge detection comparable to Gaussian filter/median filter etc.
- Image processing needs improvement

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QUESTIONS?